



Detection Bank: An Object Detection Based Video Representation for Multimedia Event Recognition



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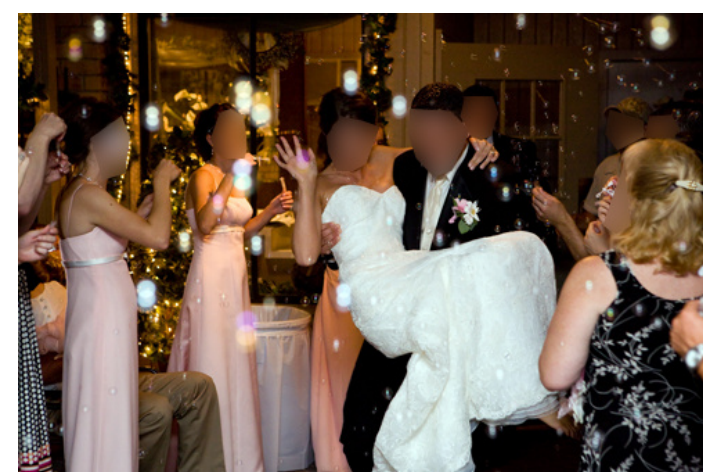
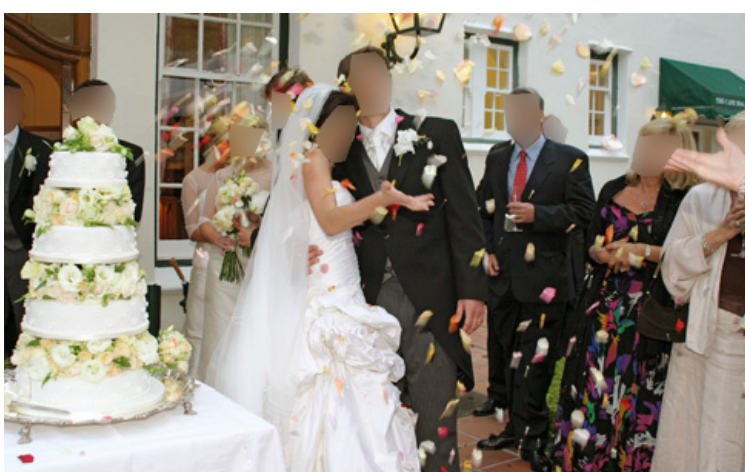
Multimedia Event Detection



Birthday Party

vs

Wedding Ceremony

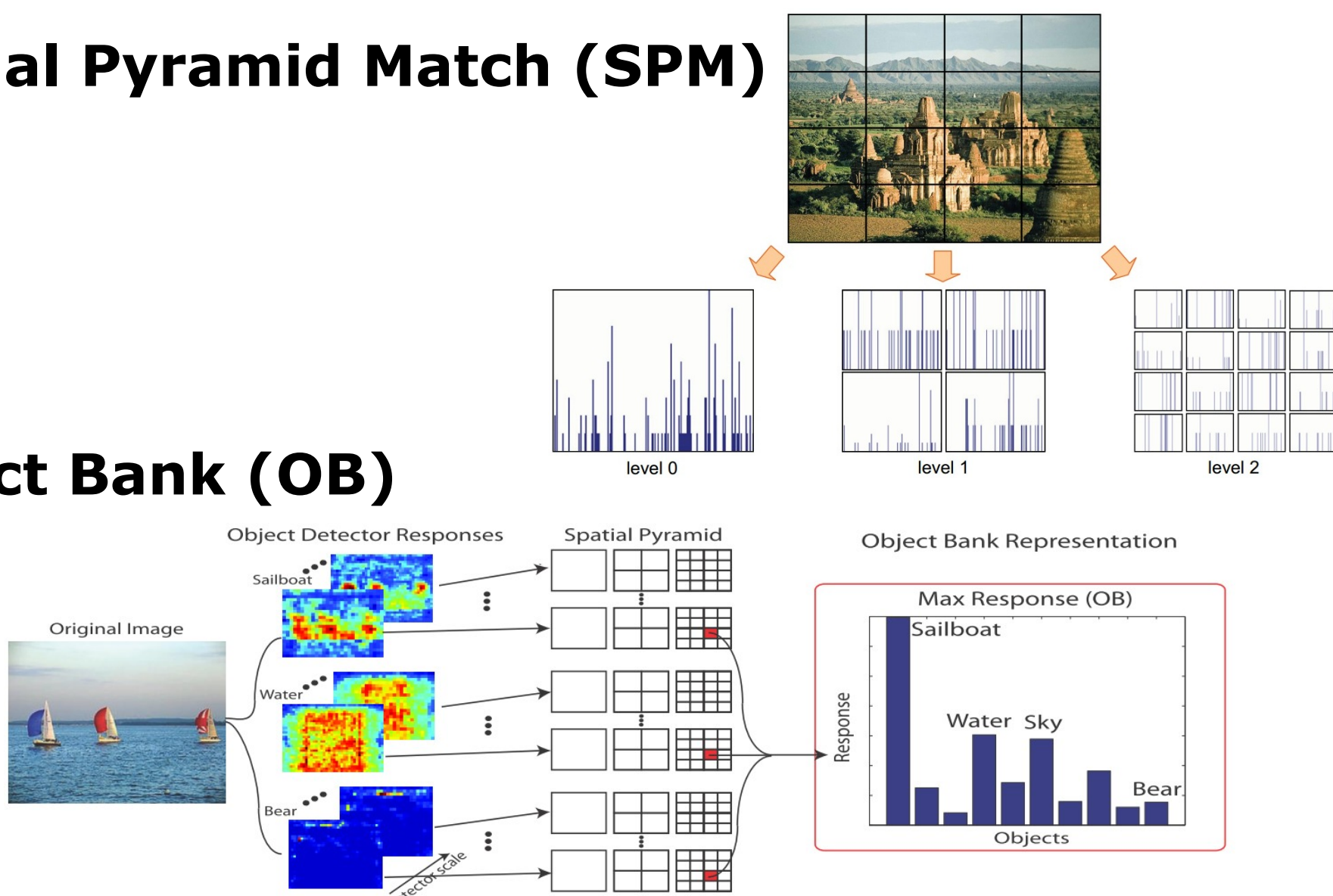


Look for: Balloon, Candle, Birthday Cake vs. Bride, Groom, Wedding Gown, Wedding Cake

Previous Work

Spatial Pyramid Match (SPM)

Object Bank (OB)



Problem

Scene-level descriptors cannot capture *fine-grained phenomena* that discriminate between events. **Object Bank** lacks immediate sense of whether or not there are *objects present in the image* and if so how many.

References

S. Lazebnik, C. Schmid, and J. Ponce. Beyond bags of features: Spatial pyramid matching for recognizing natural scene categories. CVPR, 2006.
L.-J. Li, H. Su, E. P. Xing, and L. Fei-Fei. Object bank: A high-level image representation for scene classification & semantic feature sparsification. NIPS, 2010.

Acknowledgments

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Idea

- ObjectBank omits the following steps that are standard in a detection pipeline:
 - Thresholding of score maps
 - Non-maximum suppression
 - Pooling across all scales
- We compute different *detection count statistics* to capture e.g. max number of detections, sum of detection scores, probability of detection based on the detection images from a large number of windowed object detectors.

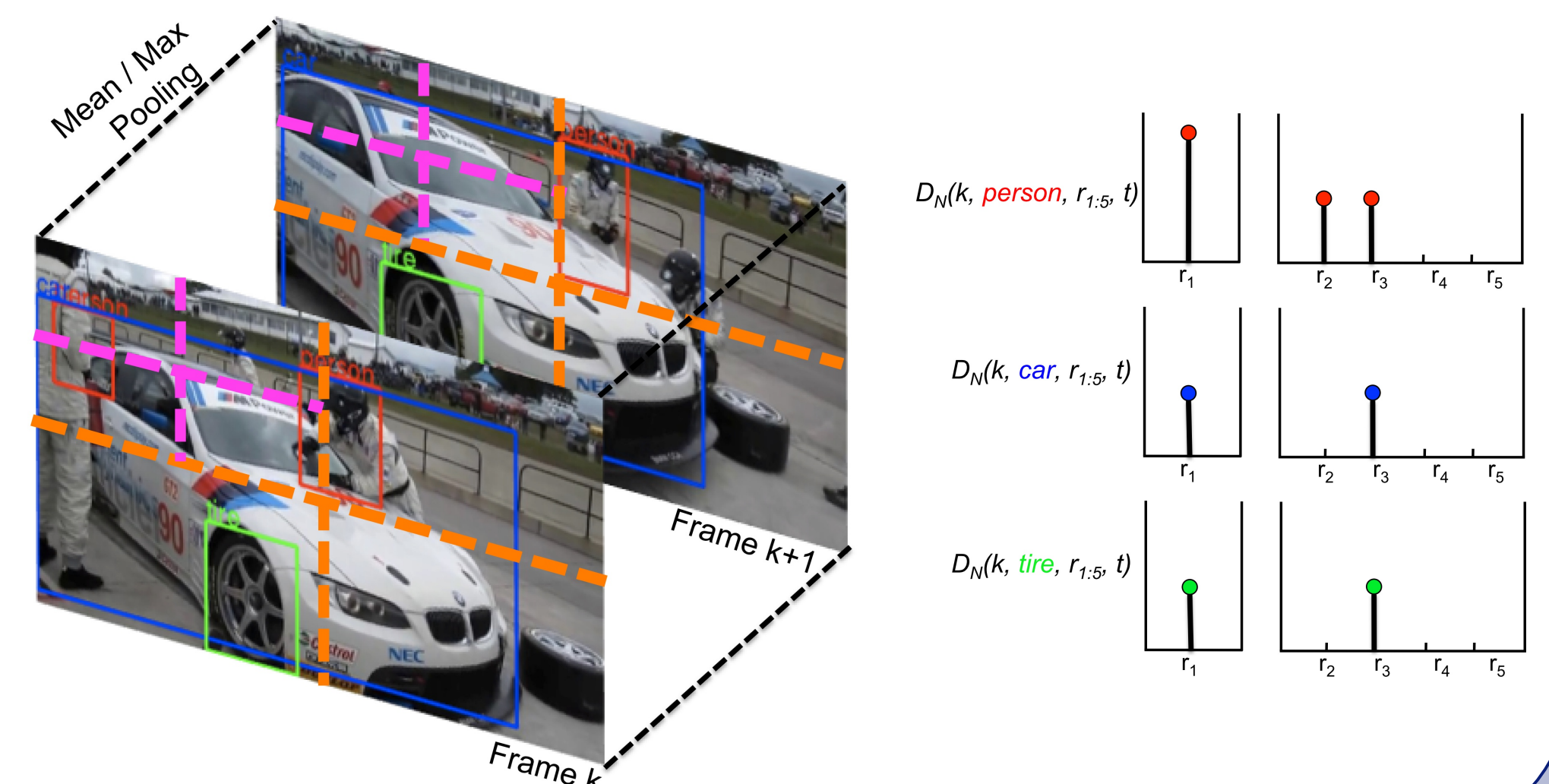
Detection Count Statistics

$$D_S(k, c, r, t) = \sum_{i=1}^P \mathbb{I}[\overline{\mathbf{b}_{c,i}} \in \mathcal{I}(r)] \mathbb{I}[s(\mathbf{b}_{c,i}) \geq t] s(\mathbf{b}_{c,i})$$

$$D_N(k, c, r, t) = \sum_{i=1}^P \mathbb{I}[\overline{\mathbf{b}_{c,i}} \in \mathcal{I}(r)] \mathbb{I}[s(\mathbf{b}_{c,i}) \geq t]$$

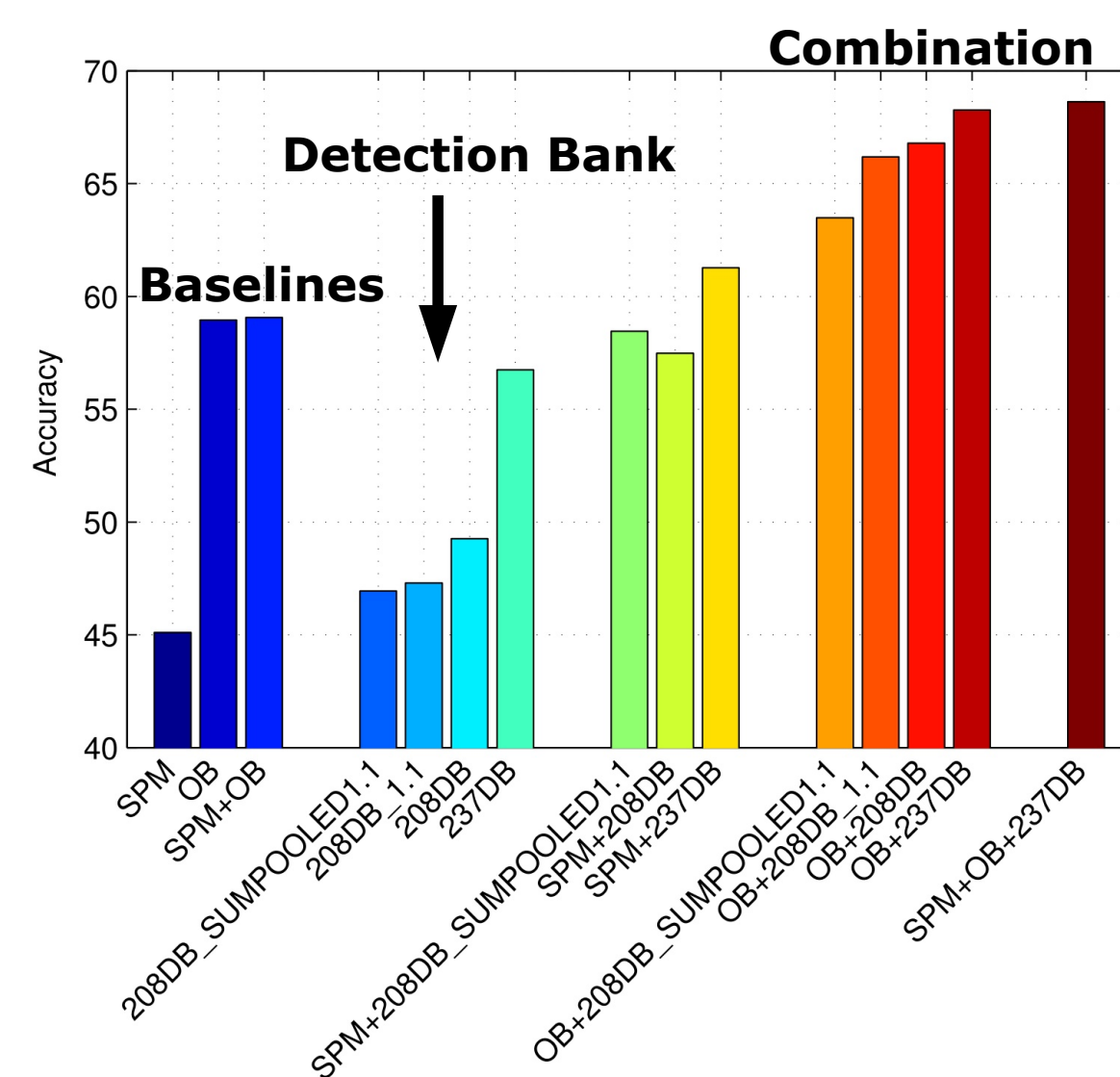
$$D_0(k, c, r, t) = \mathbb{I}\left[\sum_{i=1}^P (\mathbb{I}[\overline{\mathbf{b}_{c,i}} \in \mathcal{I}(r)] \mathbb{I}[s(\mathbf{b}_{c,i}) \geq t]) > 0\right]$$

Illustration

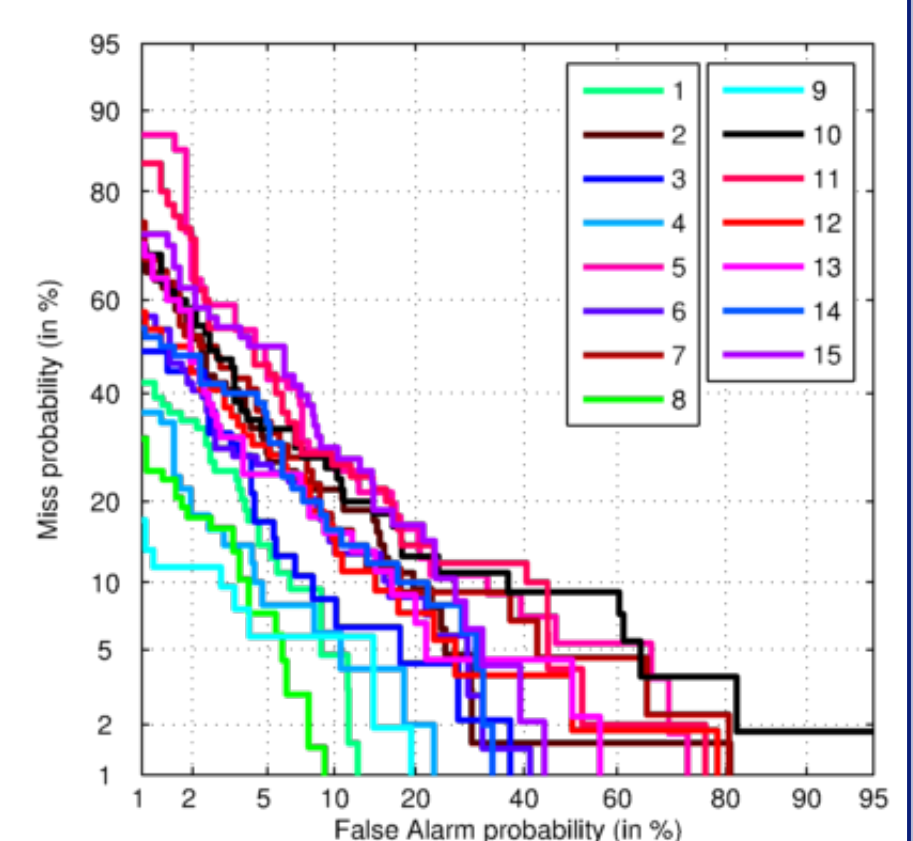


Experiments

Classification Accuracy on TRECVID MED



DET Curves for all 15 Events



Conclusion

- Significant performance increase in Multimedia Event Classification Task
- Provides complementary discriminative information to current state-of-the-art image representations such as Spatial Pyramid Matching and Object Bank